# Aaquib Tabrez

Curriculum Vitae

### Research Interests

I work at the intersection of explainability and human-robot interaction. In my research, I leverage and enhance human-machine communication to achieve value alignment and foster appropriate trust within human-robot teams. My broad interests include Explainable AI, Reinforcement Learning, Multimodal Human-Machine Communication, and Human-Robot Interaction.

### Education

- 2019 2024 **University of Colorado, Boulder**, *GPA: 4.0*, Ph.D. Candidate, *Computer Science*. (expected) Advisor: Bradley Hayes
  - 2017–2019 University of Colorado, Boulder, GPA: 4.0, MS, Mechanical Engineering.
  - 2010–2014 National Institute of Technology Karnataka, India, B. Tech, Mechanical Engineering.

### Awards and Recognition

- 2024 People's Choice Award 3MT Competition.
  Won the People's Choice Award at the 2024 CU Boulder Three Minute Thesis (3MT) competition, receiving the highest number of audience votes.
- 2024 **Doctoral Consortium at AAAI-2024**. Selected to present on "Autonomous Policy Explanations for Effective Human-Machine Teaming" at the AAAI-2024 Doctoral Consortium.
- 2023 **Doctoral Consortium at AAMAS-2023**. Selected for a workshop aimed at top early-career researchers in the field of Multi-agent systems.
- 2023 Annual Research Expo'23 Poster Presentation Award. Received best research poster presentation award at the CU Boulder's Annual Research Expo '23.
- 2022 **Robotics: Science and Systems (RSS) Pioneers**. Selected for workshop bringing together top early career researchers in robotics.
- 2022 Best Student Paper Award Runner-up at AAMAS. For the paper "Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming".
- 2022 Won Spring 2022 Annual Research Expo Event. Received the best poster presentation award at the Spring 2022 Annual Research Expo from CU Boulder.
- 2020 **IBM PhD Fellowship Finalist**. One of three students nominated by the CS department at CU Boulder.
- 2019 Best Paper Award Finalist for Technical Advances at ACM/IEEE HRI. For the paper "Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning".
- 2019 Human-Robot Interaction (HRI) Pioneers. Selected for workshop bringing together top early career researchers in HRI.
- 2019 Awtar and Teji Singh Graduate Fellowship. A \$5,000 fellowship for early career PhD students demonstrating a strong academic and research record.

#### 2016 Yuva Prerna Yatra Fellowship.

Selected as a social entrepreneur fellow to travel, study, and support local entrepreneurs in the Himalayas, leveraging regional resources to foster prosperity.

### Papers in Submission

- Asterisk (\*) denotes shared first authorship
- no paper link **Title omitted for blind review**. **Aaquib Tabrez**, Ryan Leonard, Bradley Hayes. In submission: Robotics: Science and Systems (RSS), 2024

### Journal Articles

paper link A survey of Mental Modeling Techniques in Human-Robot Teaming. Aaquib Tabrez, Matthew B. Luebbers, Bradley Hayes. Springer-Nature Current Robotics Reports, 2020

### Conference Publications

no paper link Recency Bias in Task Performance History Affects Perceptions of Robot Competence and Trustworthiness.

> **Aaquib Tabrez\***, Matthew B. Luebbers\*, Kanaka Samagna Talanki, Bradley Hayes. *To appear: Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), 2024*

paper link Autonomous Justification for Enabling Explainable Decision Support in Human-Robot Teaming.

**Aaquib Tabrez\***, Matthew B. Luebbers\*, Kyler Ruvane\*, and Bradley Hayes. *Robotics: Science and Systems (RSS), 2023* 

paper link Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming.

> **Aaquib Tabrez\***, Matthew B. Luebbers\*, Bradley Hayes. International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2022 Best Student Paper Runner-up (Top 2 of 629 submissions).

# paper link Asking the Right Questions: Facilitating Semantic Constraint Specification for Robot Skill Learning and Repair.

**Aaquib Tabrez\***, Jack Kawell\*, Bradley Hayes. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2021* 

### paper link Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning.

**Aaquib Tabrez**, Shivendra Agrawal, Bradley Hayes. *ACM/IEEE International Conference on Human Robot Interaction (HRI), 2019* Best Technical Paper Runner-up.

### Workshop Publications

### no paper link Autonomous Policy Explanations for Effective Human-Machine Teaming.

Aaquib Tabrez.

Doctoral Consortium at the AAAI Conference on Artificial Intelligence, 2024

# paper link Effective Human-Machine Teaming through Communicative Autonomous Agents that Explain, Coach, and Convince.

#### Aaquib Tabrez

Doctoral Consortium at the International Conference on Autonomous Agents and Multiagent Systems, 2023

paper link	Augmented Reality and Proxy Grippers Improve Demonstration-based Robot Skill
	Learning.
	Carl L. Mueller, Matthew B. Luebbers, <b>Aaquib Tabrez</b> , and Bradley Hayes. Proceedings of the Workshop on Life-Long Learning with Human Help (L3H2), 2023
paper link	Mediating Trust and Influence in Human-Robot Interaction via Explainable AI.
	<b>Aaquib Tabrez</b> , Bradley Hayes. Pioneers Workshop at Robotics: Science and Systems (RSS), 2022
paper link	Augmented Reality-Based Explainable AI Strategies for Establishing Appropriate Reliance
	and Trust in Human-Robot Teaming.
	Matthew B. Luebbers*, Aaquib Tabrez*, Bradley Hayes.
	Workshop on Virtual, Augmented and Mixed Reality for Human-Robot Interaction (VAM-HRI), 2022
paper link	Solutions for Socially Intelligent HRI in Real-World Scenarios (SSIR-HRI).
	Companion of the ACM/IEEE International Conference on Human-Robot Interaction, 2021
paper link	Interactive Constrained Learning from Demonstration Using Visual Robot Behavior
	Counterfactuals.
	Carl Mueller, <b>Aaquib Tabre</b> z, Bradley Hayes Workshop on Accessibility of Robot Programming and Work of the Future at RSS, 2021
paper link	Emerging Autonomy Solutions for Human and Robotic Deep Space Exploration.
	Matthew B. Luebbers*, Christine T. Chang*, <b>Aaquib Tabrez*</b> , Jordan Dixon*, Bradley Hayes. SpaceCHI: Human-Computer Interaction for Space Exploration, 2021
paper link	Automated Failure-Mode Clustering and Labeling for Informed Car-To-Driver Handover
	in Autonomous Vehicles.
	<b>Aaquib Tabrez*</b> , Matthew B. Luebbers*, Bradley Hayes. Workshop on Assessing Explaining and Conveying Robot Proficiency for Human-Robot Teaming 2020
naper link	Improving human-robot interaction through explainable reinforcement learning
puper mix	Aaguib Tabrez. Bradley Haves.
	Companion of the ACM/IEEE International Conference on Human-Robot Interaction, 2019
	Teaching & Research Assistantships
Spring 2021 -	Army Research Lab STRONG Program: Strengthening Teamwork for Robust Operations
Present	in Novel Groups, University of Colorado Boulder, CO.
	Research Assistant, Prof. Bradley Hayes
Fall 2020	CSCI 5302/4302: Advanced Robotics, University of Colorado Boulder, CO.
	Teaching Assistant, Prof. Bradley Hayes
Fall 2020	CSCI 3302: Introduction to Robotics, University of Colorado Boulder, CO.
	Teaching Assistant, Prof. Bradley Hayes
Spring 2020	<b>CSCI 5922:</b> Neural Networks and Deep Learning, University of Colorado Boulder, CO. Teaching Assistant Profs. Adam Bloniarz & Shumin Wu
Fall 2010	CSCI 3302: Introduction to Robotics University of Colorado Boulder CO
1 dii 2015	Teaching Assistant, Prof. Bradley Hayes
Spring 2019	CSCI 5322: Algorithmic Human-Robot Interaction, University of Colorado Boulder, CO.
1 0	Course Grader, Prof. Bradley Hayes
Spring 2018	MCEN-4026: Manufacturing Processes and Systems, University of Colorado Boulder, CO.
	Course Grader, Prof. Jenifer Blacklock
	Workshop Committee Leadership
August 2023	Workshop on Human-Robot Interaction for Explainability in Robotics. RO-MAN 2023
	Co-Organizer

- June 2023 RSS Pioneers 2023 Workshop, RSS 2023. Program Committee Chair
- March 2021 Solutions for socially intelligent HRI in real-world scenarios workshop, HRI 2021. Co-Organizer
- March 2021 HRI Pioneers 2021 Workshop, HRI 2021. Program Chair
- August 2020 Solutions for socially intelligent HRI in real-world scenarios workshop, RO-MAN 2020. Co-Organizer
- March 2020 HRI Pioneers 2020 Workshop, HRI 2020. Program Chair

#### Invited Panels and Talks

- 2023 **Talking Robotics**, Building Trust and Transparency through Explainable Multimodal Communication.
- 2021 **University of Colorado Boulder**, *Mediating Trust and Influence in Human-Robot Interaction via Explainable AI*, Robotics Summer Seminar Series.

### Professional Experience

- 2014 2016 **Daimler**, *Chennai*, *India*. Procurement Manager
- Aug 2012 Kudremukh Iron Ore Company, Kudremukh, India. Dec 2012 Industrial Intern

### Research Mentorship

- 2024 David Chaparro, Masters, CU Boulder.
- 2023 Kyler Ruvane, Masters, CU Boulder.
- 2023 Nathan Howard, Masters, CU Boulder.
- 2022 2023 Kanaka Talanki Sreenivasa Murthy, Masters, CU Boulder.
- 2021 2022 Karthik Siddaramanna, Masters, CU Boulder.
- 2020 2021 Aditi Periyannan, Undergraduate, Tufts University.
  - 2019 Felix Moses, Berkeley High School.
    - 2019 Stephen Kwak, Bellarmine High School.
- 2018 2019 Xi Hu, Undergraduate, CU Boulder.

### Conference and Journal Review

IEEE Robotics and Automation Letters (RA-L) ACM Transactions on Human-Robot Interaction (T-HRI) International Journal of Human-Computer Interaction (IJHCI) ACM/IEEE International Conference on Human-Robot Interaction (HRI) IEEE International Conference on Robotics and Automation (ICRA) IEEE International Conference on Intelligent Robots and Systems (IROS) CHI: Conference on Human Factors in Computing Systems (CHI) IEEE International Conference on Robot and Human Interactive Communication (RO-MAN) Explainable AI Planning Workshop (XAIP), ICAPS Workshop on Explainable Artificial Intelligence (XAI), IJCAI Companion of the Robotics: Science and Systems (RSS Pioneers)